



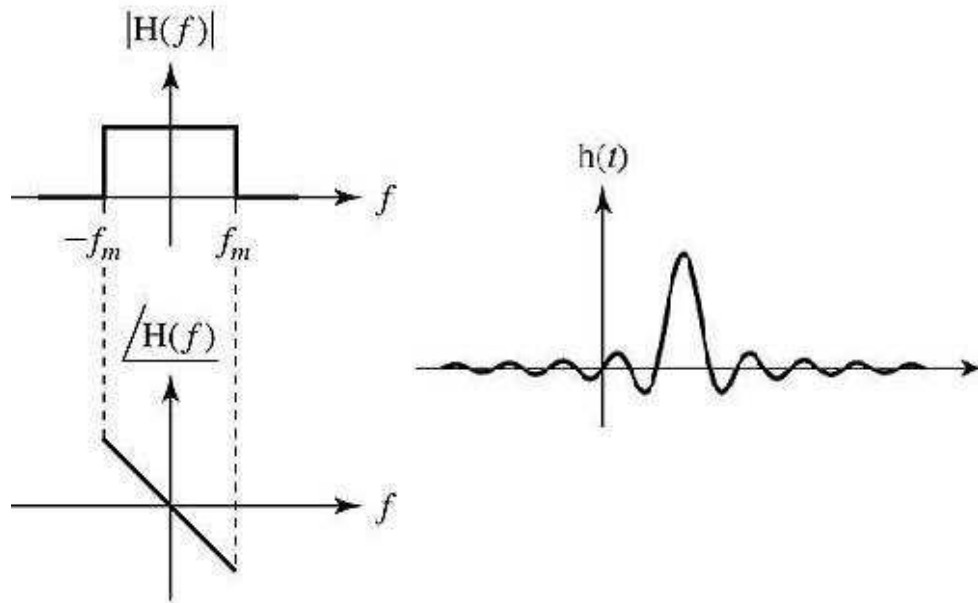
ENSC380  
Lecture 21

Objectives:

- Signals and Systems Fourier Analysis:
  - Causal Filters

# Ideal vs. Causal Filters

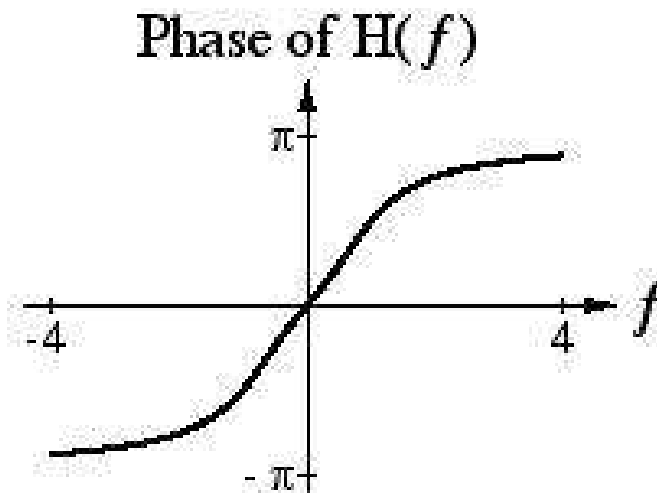
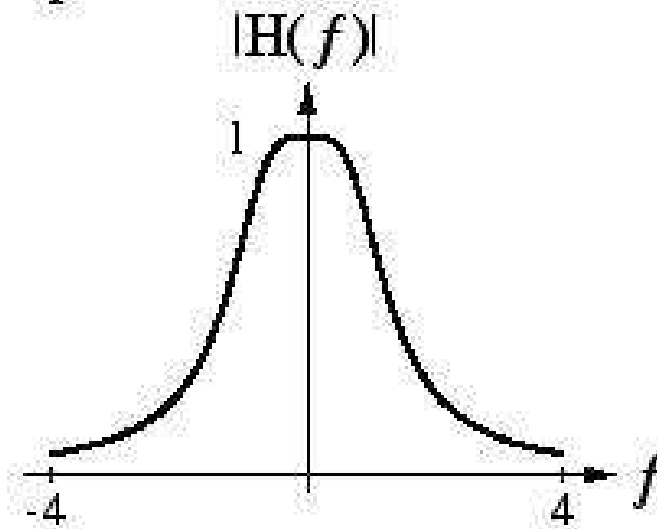
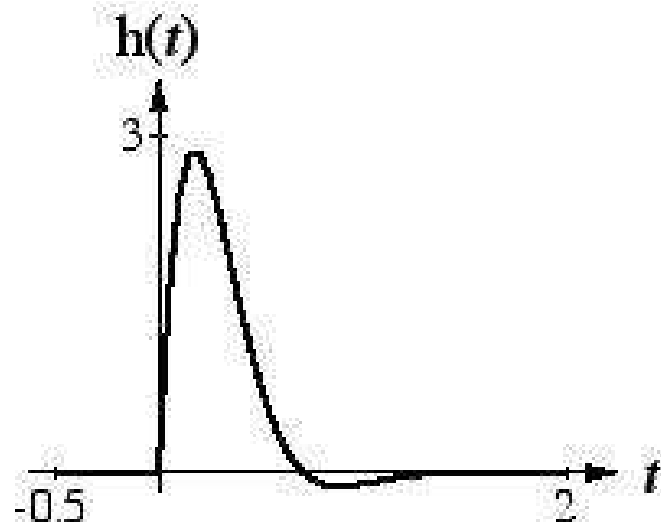
- The filters mentioned in Lecture 20 are “ideal” filters. For example, the transfer function and impulse response of the ideal CT LP-filter are:



- For a filter to be realizable, it should be “Causal”. Is the above filter causal? Why?
- It is however possible to closely approximate ideal filters with causal filters.
- An example of an approximation for the LP-filter is given:

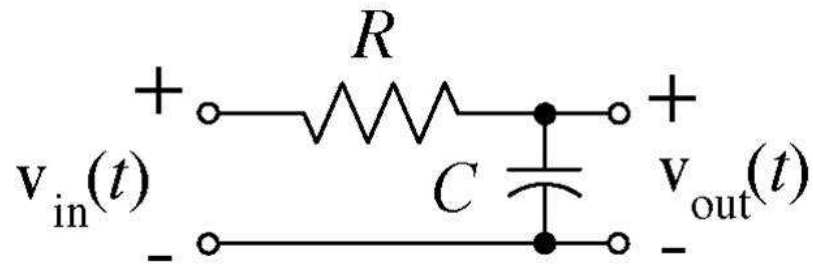
# Causal Lowpass Filter

## Causal Lowpass



# Example 1:RC LPF

Let's study the RC Low Pass Filter (LPF) below:



## Example 2

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Find the output voltage of the above filter, if the input voltage is  $v_i(t) = \sin(2\pi f_0 t)$ .

## Example 3: RC-LPF vs Ideal LPF

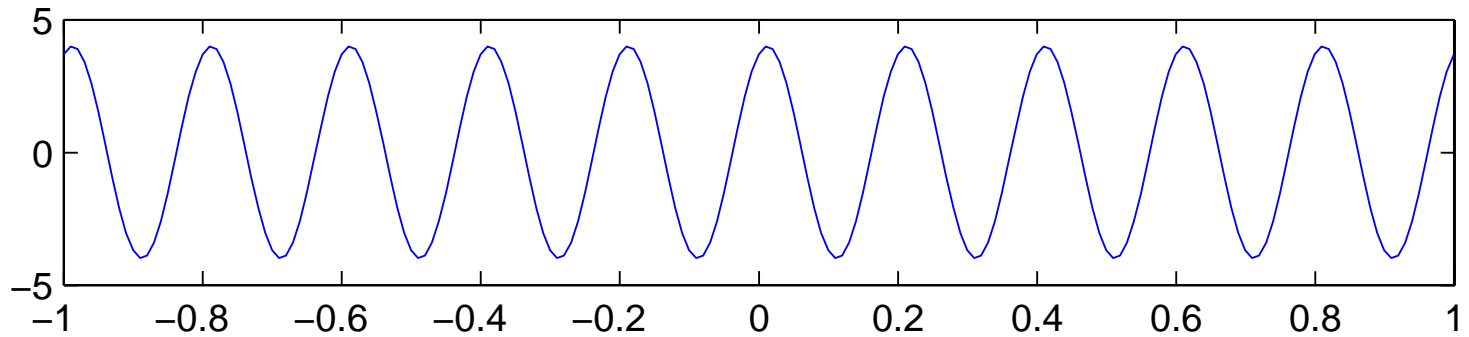
An ideal LPF with bandwidth  $f_c = 10(\text{kHz})$  and a phase  $\angle H(f) = -\frac{\pi}{40} f$  ( $f$  is in kHz), has been approximated with an RC LPF with  $\frac{1}{2\pi RC} = 10(\text{kHz})$ . The input voltage to both filters is

$$v_i(t) = 4 \cos(2\pi f_1 t) + 3 \sin(2\pi f_2 t) \quad \text{where } f_1 = 5\text{kHz} \quad f_2 = 15\text{kHz}$$

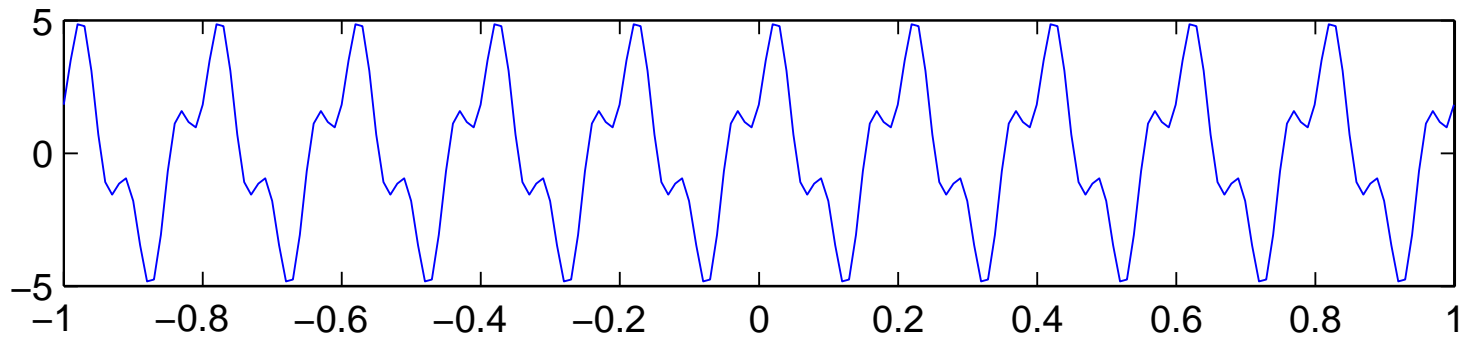
Find the output voltages of the two filters and compare.

# Example 3 (Cont.)

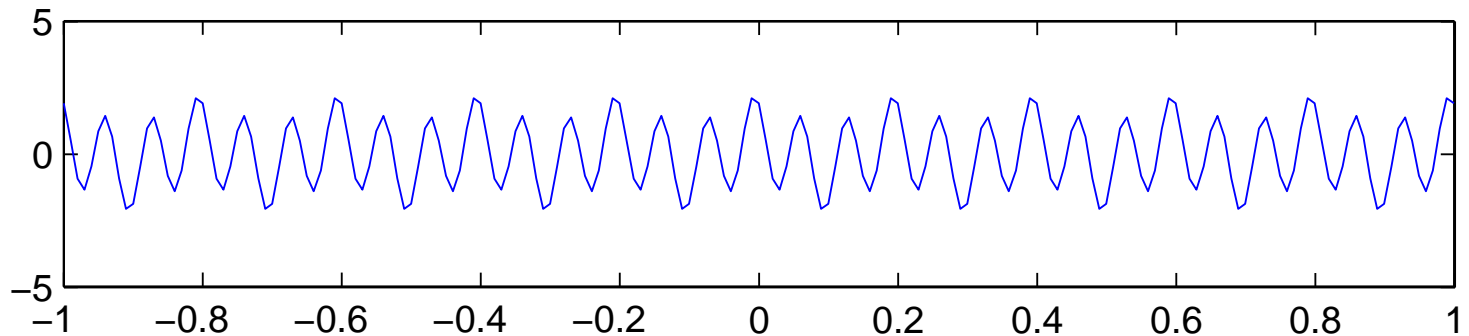
Output of Ideal LPF



Output of RC LPF

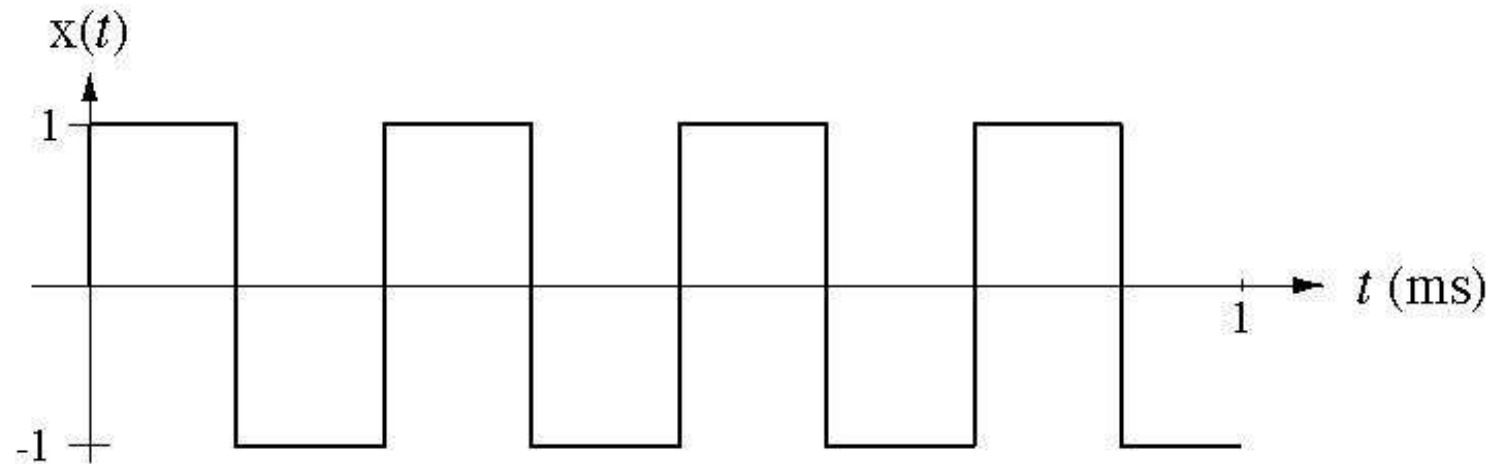


Difference



# Example of a Causal HPF

## Excitation



## Response

