ENSC380 Lecture 7

Objectives:

- Learn how to find the answer to the homogeneous difference equation
- Learn how to find the **impulse response** of the LTI DT system

Homogeneous Response

• The difference equation:

$$a_n y[n] + a_{n-1} y[n-1] + \ldots + a_{n-D} y[n-D] = 0$$

is called a homogeneous difference equation.

 The general form of the function that can satisfy the homogeneous difference equation is:

$$y_h[n] = A\alpha^n$$

• Replace y[n] with $y_h[n]$ in the above equation to find α :

• $y_h[n] = A\alpha^n$ is called the **eigenfunction** of the difference equation.

Impulse Response of DT Systems



Impulse Response (Cont.)

Since the forcing function (input signal) to the system is zero for all n < 0, we can easily see that

$$y[n] =$$
 for $n < 0$

• Also for n > 0, the difference equation is:

$$a_n y[n] + a_{n-1} y[n-1] + \ldots + a_{n-D} y[n-D] =$$

which means

$$y[n] =$$
 for $n > 0$

• How about for n = 0? For n = 0 it is easy to find y[0] directly from the equation:

This can be used as the initial condition for y[n]. We will see this through examples.

Example 1

Recall the example in Lecture 6, where we were given the impulse response:

$$8y[n] + 6y[n-1] = x[n]$$
, $h[n] = \frac{1}{8}(-\frac{3}{4})^n u[n]$

Now, let's find this impulse response for ourselves!

Example 2

Find the impulse response of this system:

$$y[n] = x[n] - x[n-1]$$

Example 3

Find the impulse response of this system:

