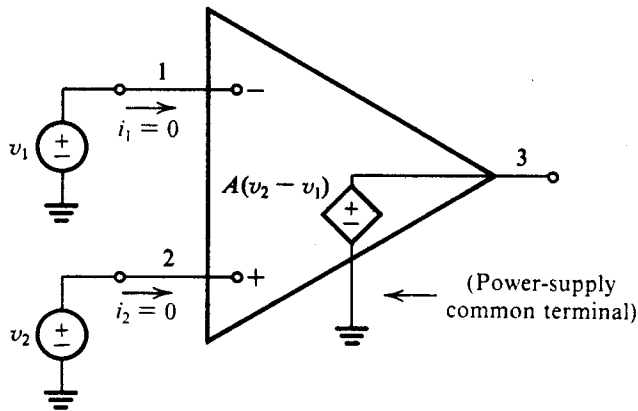


2. OPERATIONAL AMPLIFIERS

2.1 Basic Configurations

- The op amp is the easiest implementation method for most low power analog applications under 1 MHz or so.
but there are op amps to 40 MHz, and to 50 W! \$\$.
- A typical op amp has a couple of dozen transistors inside – but you don't have to know how it's built to build bigger things from it.
- Always used with feedback and other components, and they are what determine the function.



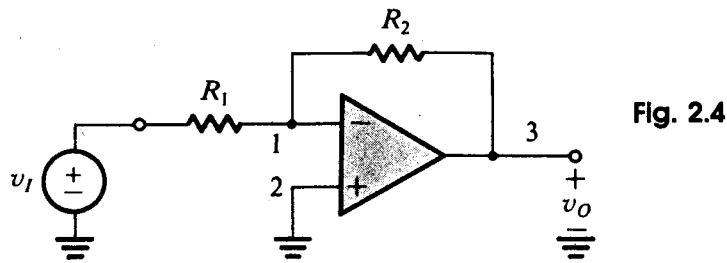
- Idealized model of an op amp.

We also have two power supply connections, usually $+15V, -15V$

though some use other values. Also possible (uncommon) to use one sided supply.

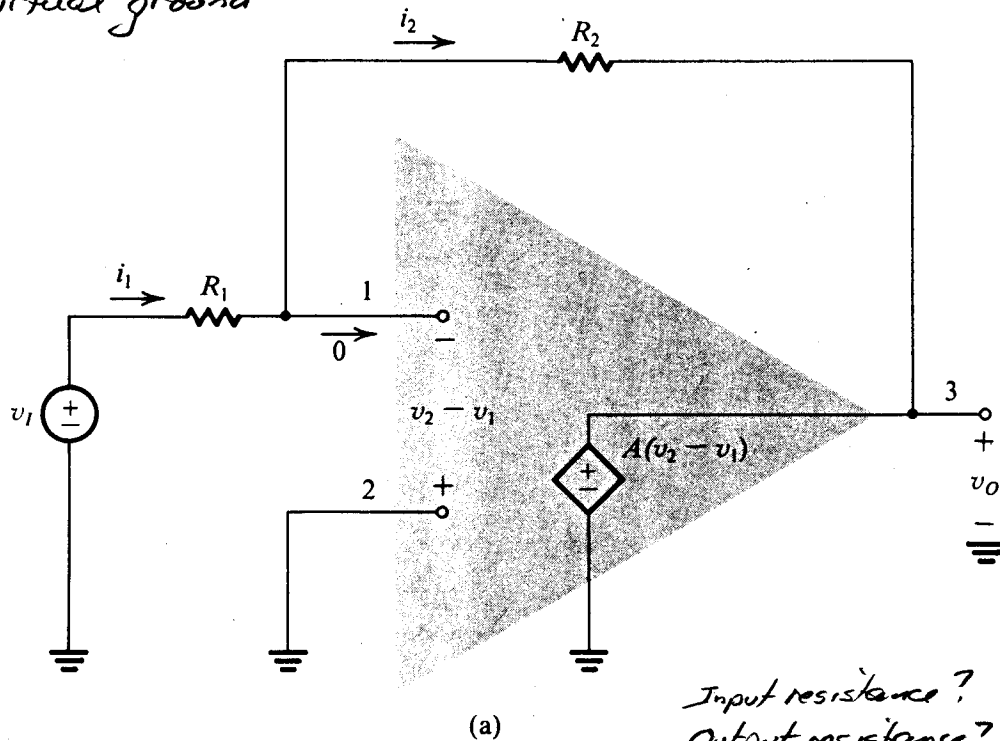
- Ideal model gives good first approximation to function.
 - infinite input resistances
 - zero output resistance
 - responds only to difference $v_2 - v_1$
 - huge voltage gain (infinite, ideally)

This is the most basic feedback configuration:



Equivalent circuit:

*- negative feedback keeps v_1 close to v_2 (i.e. zero), same polarity as v_I
"virtual ground"*



*Input resistance?
Output resistance?
Voltage gain?*

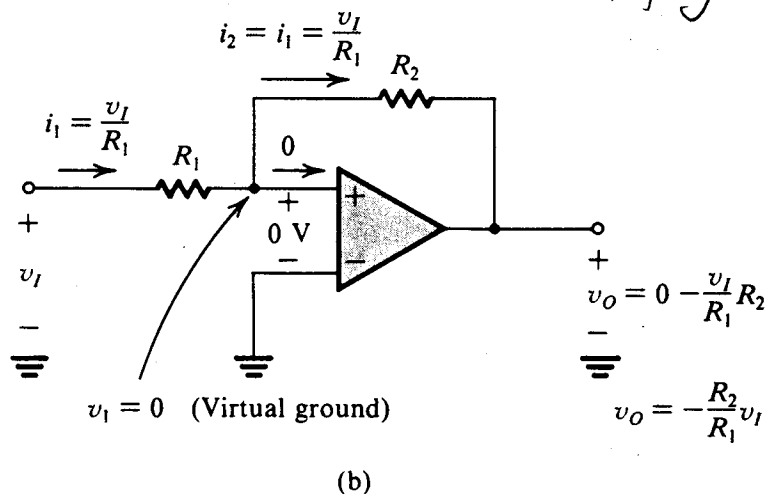
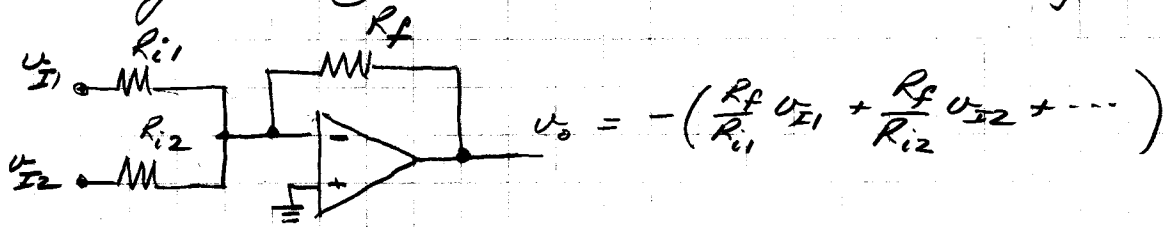


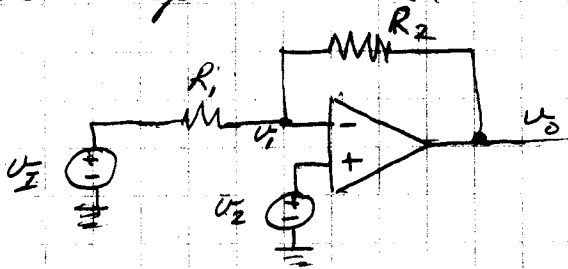
Fig. 2.5

- Because of virtual ground, we can make a summing amp

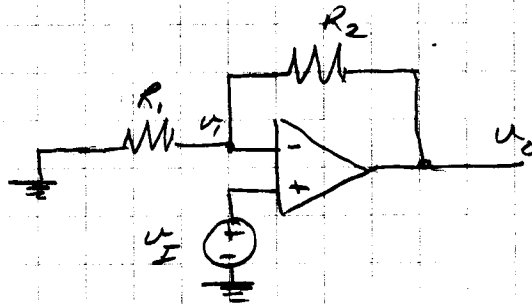


selection of resistors gives different weights per branch

- More generally, if $U_2 \neq 0$, the same argument shows that negative feedback keeps $U_1 \approx U_2$, so that "virtual ground" is just a special case



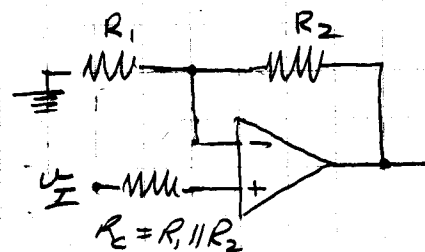
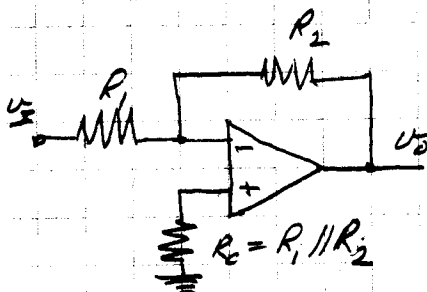
which leads directly to the noninverting configuration



$$U_O = U_I + R_2 \frac{U_I}{R_i} \\ = U_I \left(1 + \frac{R_2}{R_i} \right)$$

- Simplified design guidelines:

— Because of bias currents (Text, 2.12), make resistances seen by +, - terminals equal, using compensating resistor.



- Check to make sure output voltage swing does not exceed supply, less some "backoff".
- Resistances: if too small, then unnecessary loading on source or amp; if too big, then thermal noise, also current into $+$, $-$ inputs not negligible
So choose in the range $1\text{ k}\Omega$ to $100\text{ k}\Omega$, and above $10\text{ k}\Omega$ if possible
- Keep closed loop gains much less than open loop (typically under 100)
- Check max current, max power dissipation in amp.

2.2 Differential Amplifier

• Here's a common problem in instrumentation:

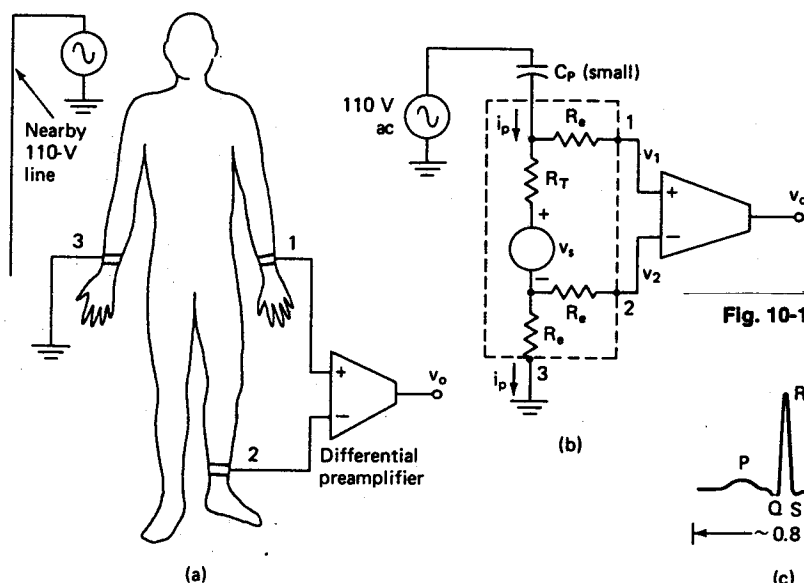


Fig. 10-11 EKG: (a) measurement and (b) equivalent circuit; (c) signal.

from D. Wobschall
Circuit Design for
Electronic Instrumentation
McGraw Hill 1979

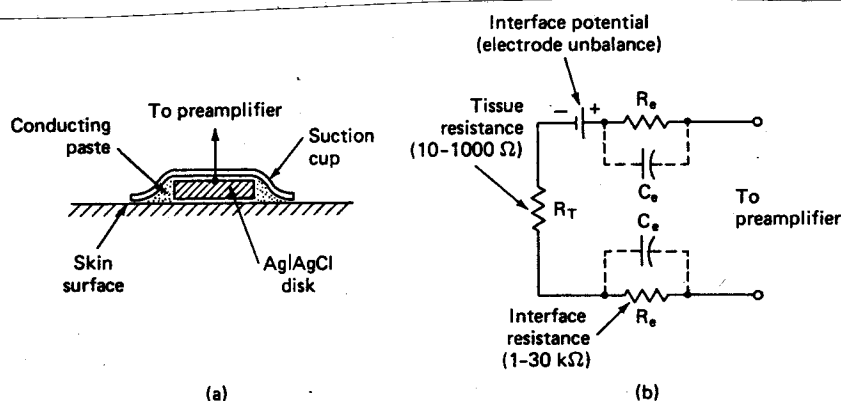


Fig. 10-10 Surface or skin electrodes: (a) construction details; (b) electrical equivalent circuit for a pair of electrodes.

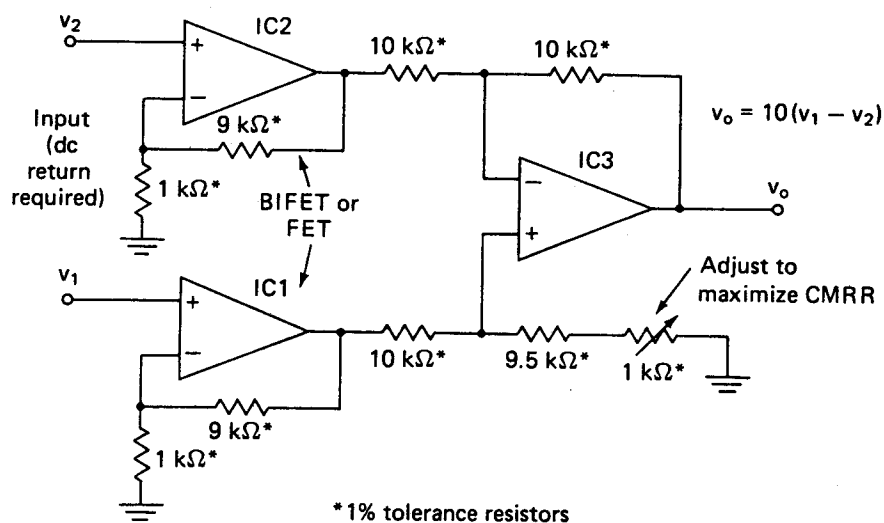


Fig. 10-12 Differential-input preamplifier, standard dc version.

Solution:

two buffer amps with gain (how much?) followed by a differential amp

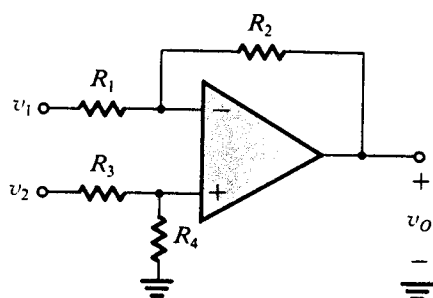


Fig. 2.19 A difference amplifier.

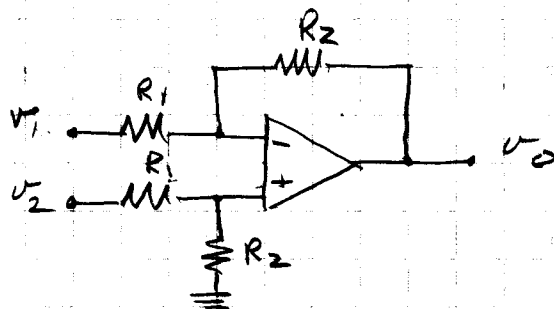
Since $v_- = v_+$

$$\frac{1}{R_1} \left(v_1 - \frac{R_2}{R_3 + R_4} v_2 \right) = \frac{1}{R_2} \left(\frac{R_4}{R_3 + R_4} v_2 - v_o \right)$$

$$v_o = -\frac{R_2}{R_1} v_1 + \frac{1 + R_2/R_1}{1 + R_3/R_4} v_2$$

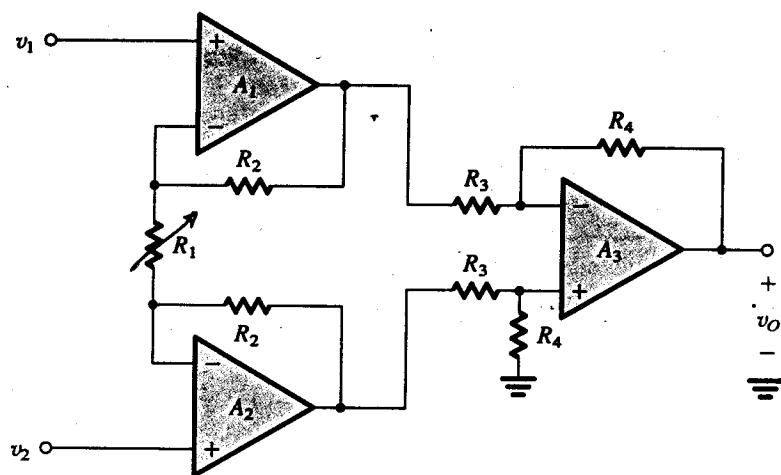
Choose $R_2/R_1 = R_4/R_3$, and

$$v_o = \frac{R_2}{R_1} (v_2 - v_1)$$



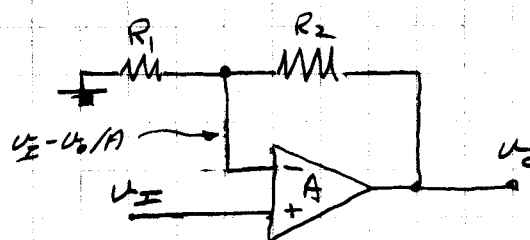
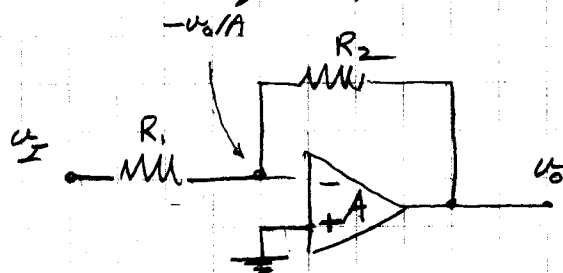
input resistance, common mode
 $\frac{1}{2}(R_1 + R_2)$

input resistance, differential mode
 $2R_1$



a better circuit.
 - high input impedance
 - single gain adjustment

2.2 Finite and Frequency Dependent Open Loop Gain



Open loop gain is finite, though usually large.

$$\frac{v_I + v_o/A}{R_1} = -\frac{-v_o/A - v_o}{R_2}$$

$$\frac{v_I - v_o/A}{R_1} = \frac{v_o - v_I + v_o/A}{R_2}$$

$$\frac{v_o}{v_I} = G = \frac{-R_2/R_1}{1 + (1 + R_2/R_1)/A}$$

$$\frac{v_o}{v_I} = G = \frac{1 + R_2/R_1}{1 + (1 + R_2/R_1)/A}$$

$$= -\frac{R_2}{R_1} \frac{\beta A}{1 + \beta A}$$

$$= (1 - \beta^{-1}) \frac{\beta A}{1 + \beta A}$$

$$\beta = \frac{R_1}{R_1 + R_2}$$

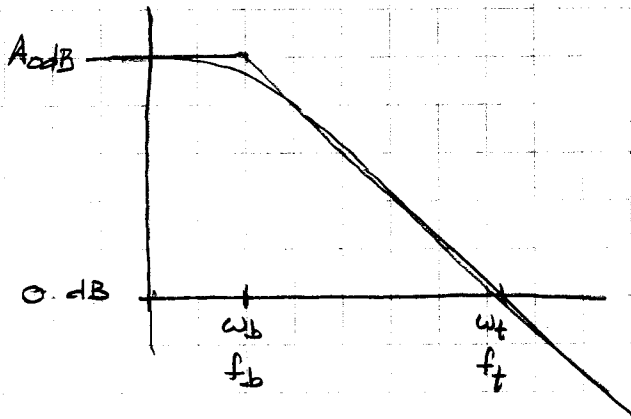
$$= \left(1 + \frac{R_2}{R_1}\right) \frac{\beta A}{1 + \beta A}$$

$$= \frac{1}{\beta} \frac{\beta A}{1 + \beta A}$$

If $\beta A \gg 1$, then G (closed loop gain) not sensitive to the actual value, and $v_+ \approx v_-$.

- The open loop gain depends on frequency like a STC Lowpass

$$A = \frac{A_0}{1 + j\omega/\omega_b}$$



unity gain bandwidth

$$\omega_t = A_0 \omega_b \quad f_t = A_0 f_b$$

We don't much care what the gain is around ω_b or less (Why?). At higher frequencies,

$$A \approx \frac{A_0 \omega_b}{j\omega} = \frac{\omega_t}{j\omega} = \frac{f_t}{jf} \angle -90^\circ$$

- Effect on closed loop

$$\frac{\beta A}{1 + \beta A} = \frac{1}{1 + \frac{1}{\beta A}} = \frac{1}{1 + j\omega/\beta\omega_t}$$

The 3 dB bandwidth is now $\omega_{3dB} = \beta\omega_t < \omega_t$

Note that $\beta = \frac{1}{G}$ for noninverting, so if you want more gain, you sacrifice bandwidth ω_{3dB} . In fact,

$$G \omega_{3dB} = \omega_t = \text{constant} \quad (\text{non inverting})$$

$$G f_{3dB} = f_t$$

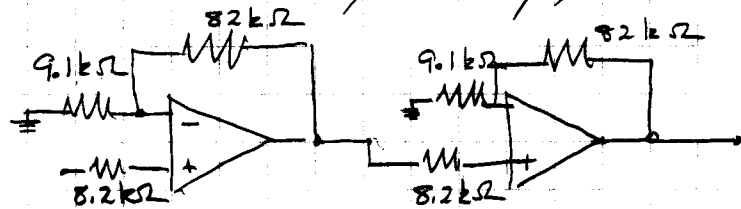
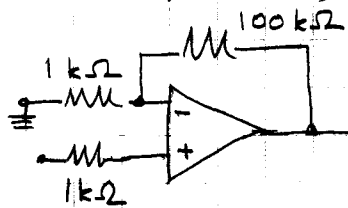
and

$$(1 + G) f_{3dB} = f_t \quad (\text{inverting})$$

- The constant gain bandwidth product is very important when you deal with wideband signals. For example, suppose the signal has 20 kHz bandwidth and the op amp has 1 MHz unity gain bandwidth. If we need 40 dB of amplification, is there a problem?

- we need an amplitude gain $A_v = 100$. This makes $f_{3dB} = 1\text{ MHz} / 100 = 10\text{ kHz}$. The signal will be grossly distorted.

- But if we did it in two stages of 20 dB ($A_v = 10$), then each stage has $f_{3dB} = 100\text{ kHz}$, and the cascade is down 6 dB at 100 kHz and only 0.34 dB (4% in amplitude) at 20 kHz. That's probably fine.



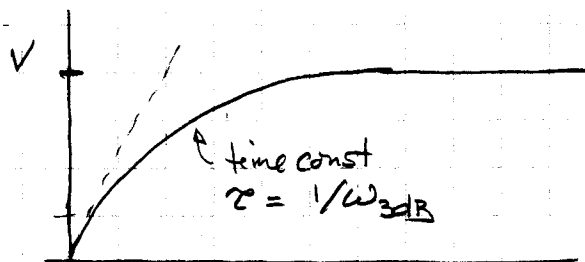
2.3 Slew Rate

- Op amps have another limitation on rate of change of the output voltage. The derivative is limited to the slew rate

$$\left| \frac{dV_o}{dt} \right| \leq \text{slew rate} \quad (0.5 \text{ V}/\mu\text{s} \text{ for } 741)$$

This shows up for signals with large amplitude and/or high frequency.

Example — step response,

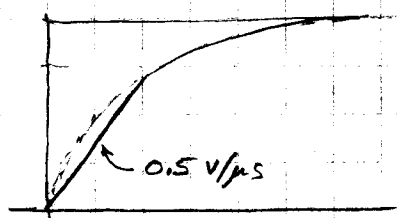


$$V(1 - e^{-\omega_{3dB}t})$$

initial slope $V\omega_{3dB} = 2\pi V f_{3dB}$

If $2\pi V f_{3dB} < \text{slew rate}$, no problem, amplifier behaves as predicted by STC model.

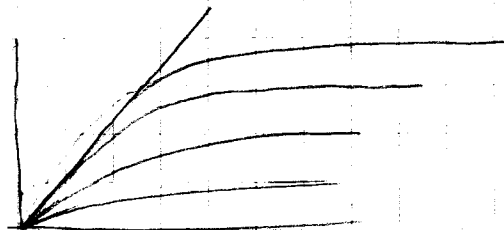
But suppose $f_{3dB} = 20 \text{ kHz}$, $V = 10 \text{ V}$ and it's a 741?



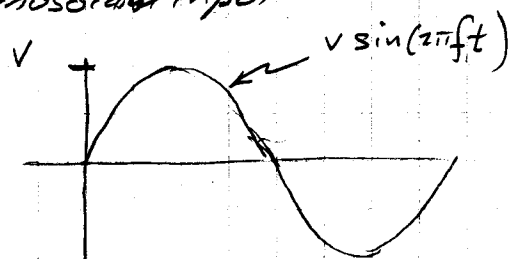
$$2\pi V f_{3dB} = 1.25 \text{ volts}/\mu\text{s}$$

initial slope

Note that if $V = 4 \text{ V}$, then $2\pi f_{3dB} V \approx 0.5 \text{ V}/\mu\text{s}$



For sinusoidal input

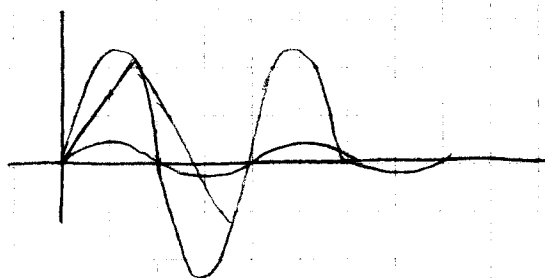


max slope $2\pi f V$

We could design a 100 kHz bandwidth, and feel safe with a 50 kHz sine wave. But if the amplitude V is

$$V > \frac{\text{slew rate}}{2\pi f} = \frac{0.5 \text{ volt}/\mu\text{s}}{2\pi \cdot 50 / \text{ms}} = 1.6 \text{ volt}$$

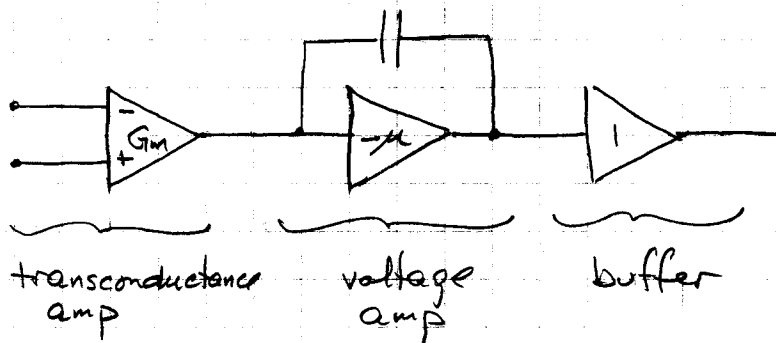
then distortion...



So the safe feeling was deceptive!

2.4 Inside The Op Amp

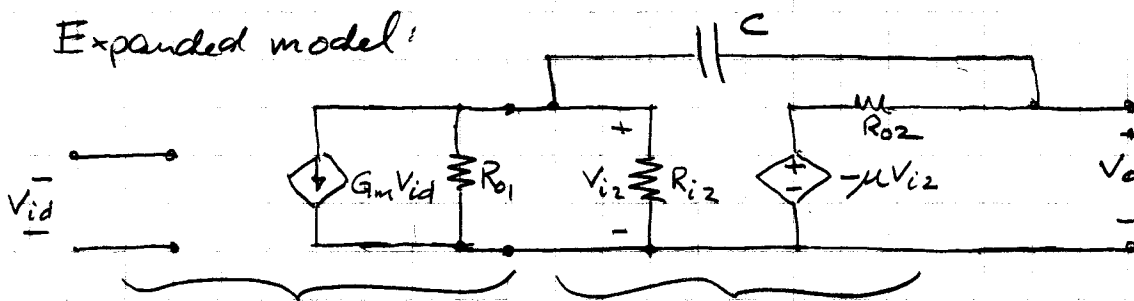
- Both the bandwidth limitation (ω_t) and the slew rate limitation have their origin in an internal capacitor



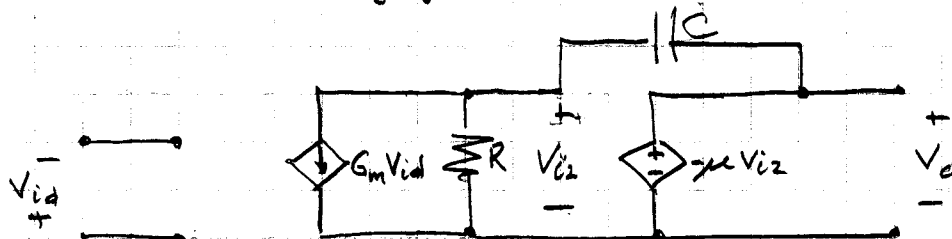
simplified model
of op amp

The capacitor is deliberate — it prevents oscillation at very high frequencies.

- Expanded model:

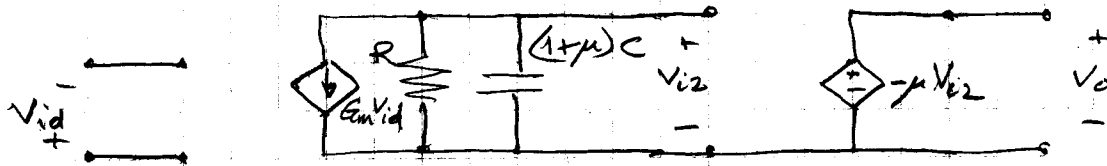


— R_{o2} is negligible. Combine $R_{o1} \parallel R_{i2} = R$



— Solve by circuit analysis, or just observe that the voltage difference across C is $(1+A) V_{i2}$, so $1+A$ times as much current as through C to ground; equivalently $(1+A)C$ to ground.

very simple equivalent



dc gain = $-\mu G_m R$, time constant = $RC(1+\mu) = \frac{1}{\omega_b}$

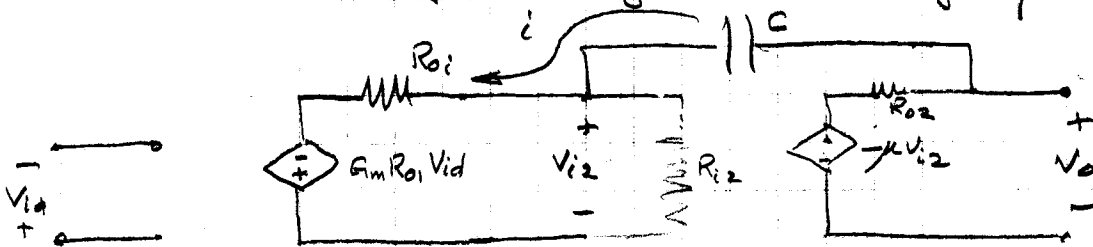
transfer function $-\frac{\mu G_m R}{1 + sRC(1+\mu)}$

unity gain frequency

$$\frac{\mu G_m R}{\omega_f RC(1+\mu)} = 1 \Rightarrow \omega_f \approx \frac{G_m}{C}$$

so the larger the compensating capacitor, the lower the unity gain frequency.

• slew rate; rearrange the original model slightly

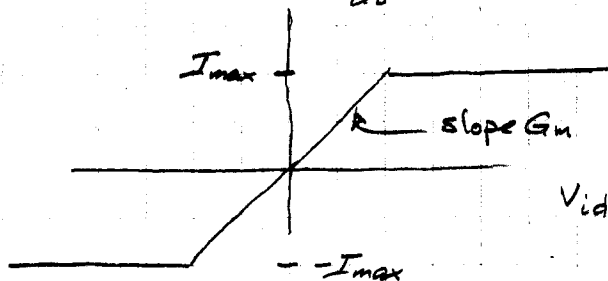


- ignore R_{i2} (very large), so all current flows through C

- virtual ground at V_{i2} (negative feedback, large μ)

$$-\frac{dV_o}{dt} = \frac{1}{C} i = \frac{G_m}{C} V_{id}$$

but voltage $G_m R_{o1} V_{id}$ is limited, so current $G_m V_{id}$ is limited, so $\frac{dV_o}{dt}$ is limited



A limitation on dV_o/dt value, as well as on V_o value.