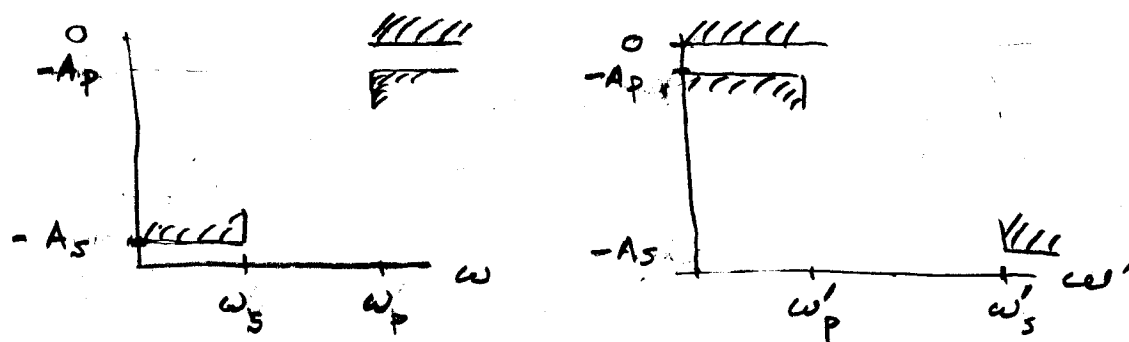


5.7 Lowpass to Highpass/Bandpass Transformation

- To this point, we have focused almost exclusively on lowpass design. What about highpass, bandpass? Fortunately, they can be obtained by transformation from lowpass designs.
- We'll do a little of it here, but read a book on active filter design if you need more.

• From Lowpass to Highpass

— Compare specs



— An inverse transformation

$$\omega \propto \frac{1}{\omega'}$$

interchanges passbands, stop bands.

The proportionality constant is a choice, but normally it is done by passband edges:

$$\frac{\omega'}{\omega_p'} = \frac{\omega_p}{\omega}$$

$$\omega' \leq \omega_p' \leftrightarrow \omega > \omega_p$$

so $\omega' = \omega_p' \frac{\omega_p}{\omega}$

This makes the lowpass stopband edge corresponding to highpass edge ω_s equal to

$$\omega_s' = \omega_p' \frac{\omega_p}{\omega_s}$$

Usually we like normalized lowpass design, so $\omega_p' = 1$ rad/s, and

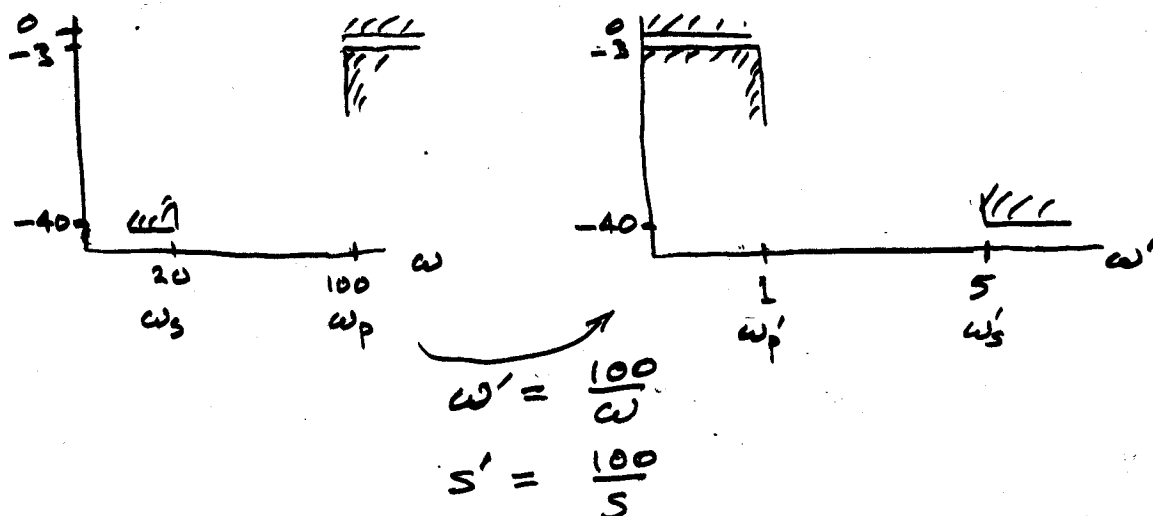
$$s' = \frac{\omega_p}{s}$$

$$\omega_s' = \frac{\omega_p}{\omega_s}$$

example Highpass spec:

stopband $A_s = 40$ dB $\omega_s = 20$ rad/s

passband $A_p = 3$ dB $\omega_p = 100$ rad/s.



- Design a lowpass to the equivalent lowpass specs in s' . This is $H'(s')$.

example: 3rd order Butterworth meets lowpass specs on previous page. For $\omega_p' = 1$ rad/s, p 5.2.10 gives

$$H'(s') = \frac{1}{s'^3 + 2s'^2 + 2s' + 1}$$

- Substitute $s' = \frac{100}{s}$ to obtain the desired highpass

$$\stackrel{\text{ex}}{=} H(s) = H'\left(\frac{100}{s}\right) = \frac{s^3}{s^3 + 200s^2 + 20,000s + 1,000,000}$$

- Hmm - we picked up some zeros. why?

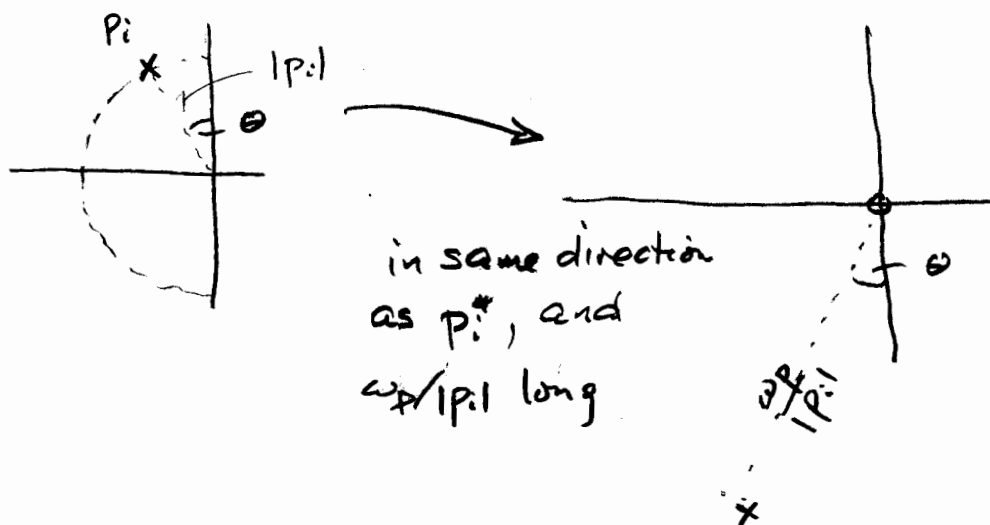
Pole movement DC+L 21.9

A typical pole

$$\frac{1}{s' - p_i'} \rightarrow \frac{1}{\frac{\omega_p}{s} - p_i'} = \frac{-s/p_i'}{s - \frac{\omega_p}{p_i'}}$$

← fresh zero

← new pole location



• Implementation

- As usual, it is easier to transform an existing normalized prototype.
- For passive circuits, the transformation $s' = \omega_p/s$ does this to caps and inductors

DC+L 21.8

lowpass proto

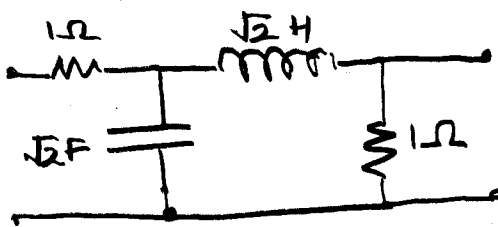
hipass

$$\text{Inductor } s'L \longrightarrow \frac{\omega_p L}{s} \quad \text{Capacitor } C = \frac{1}{\omega_p L}$$

$$\text{Capacitor } \frac{1}{s'C} \longrightarrow \frac{s}{\omega_p C} \quad \text{Inductor } L = \frac{1}{\omega_p C}$$

and it accomplishes frequency scaling on the way.

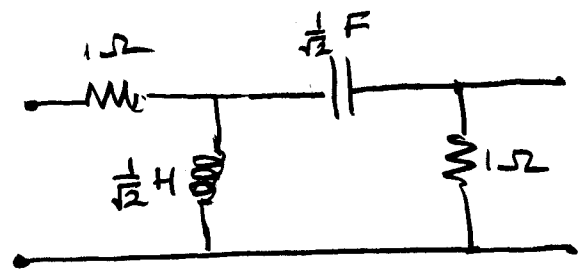
lowpass (p. 5.4.2)



Butterworth values, normalized for $\omega_p = 1$

$$s' = \frac{1}{s} \\ \omega_p = 1$$

highpass proto

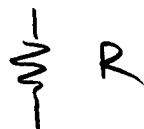
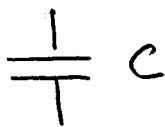


Butterworth, normalized for $\omega_p = 1$

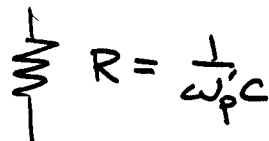
Then frequency scale, impedance scale as usual.

- For active filters, state without proof that cap/resistor interchange performs the transformation:

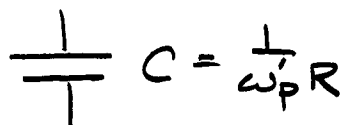
low pass



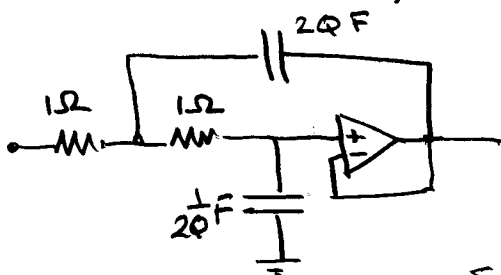
high pass



and leave
VCVS alone



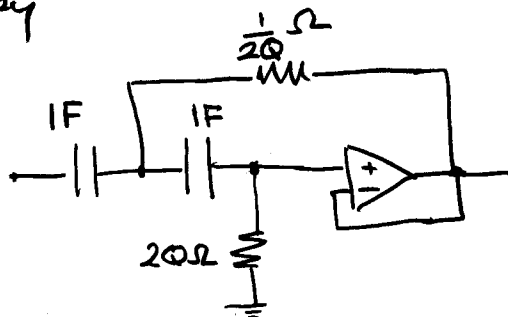
- In particular, $\omega_p' = 1$ transforms lowpass protos to highpass protos. Example: 2nd order section, Sallen-Key



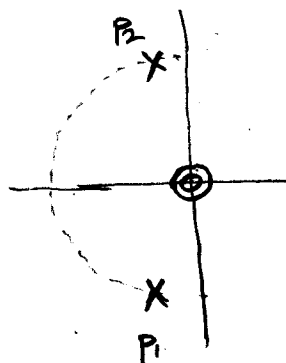
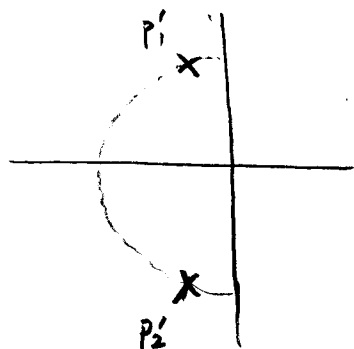
$$s' = \frac{1}{s}$$

$$\omega_p = 1$$

$$H'(s') = \frac{1}{s'^2 + \frac{1}{Q}s' + 1}$$



$$H(s) = \frac{s^2}{s^2 + \frac{1}{Q}s + 1}$$



unit radius,
so poles
stay on the
circle, but
interchange
(p 5.7.3)

— Chebyshev filters require some care, because pole radii differ. To design the highpass

→ transform specs to normalized lowpass, s'

→ select Chebyshev lowpass filter $H(s')$

→ design filter, section k with caps frequency scaled by ω_{0k} , C/ω_{0k}

→ convert to highpass using $\omega_p' = 1 \text{ rad/s}$,

so C 's $\longrightarrow \frac{1}{s} R = \frac{1}{C}$

R 's $\longrightarrow \frac{1}{s} C = \frac{1}{R}$

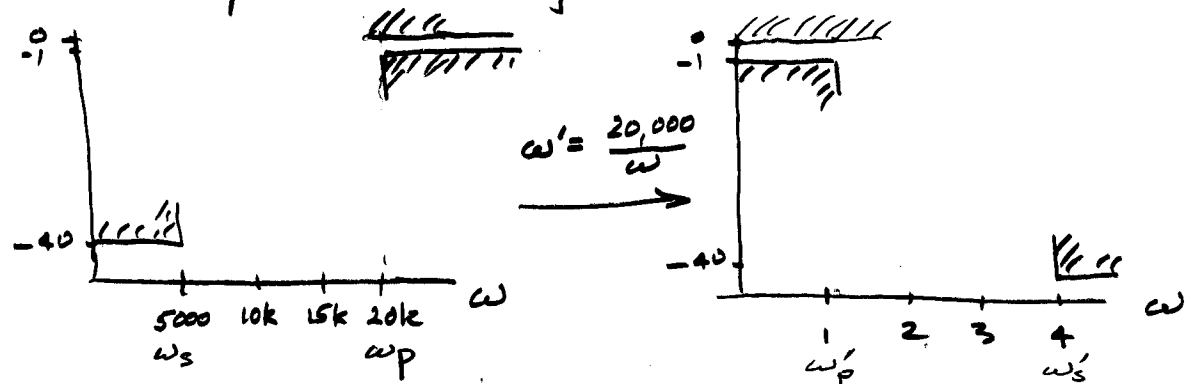
→ frequency scale to original spec. with K_f

OR combine the last three steps. For each section, a Sallen Key prototype with the right Q , but unit natural frequency is transformed by

<u>unit proto</u>	<u>Cheb LP</u>	<u>Cheb HP (norm)</u>	<u>Cheb HP</u>	<u>Final</u>
$C \parallel$	$\parallel \frac{C}{\omega_{0k}}$	$\parallel \frac{\omega_{0k}}{C}$	$\parallel \frac{\omega_{0k}}{C}$	$\parallel \frac{\omega_{0k} K_i}{C}$
$R \parallel$	$R \parallel$	$\parallel \frac{1}{R}$	$\parallel \frac{1}{R K_f}$	$\parallel \frac{1}{R K_f K_i}$

- example Design a Chebyshev highpass filter with at least 40 dB attenuation in the stopband ($\omega_s = 5 \text{ krad/s}$) and 1 dB ripple in the passband ($\omega_p = 20 \text{ krad/s}$).

→ start by transforming to normalized LP:

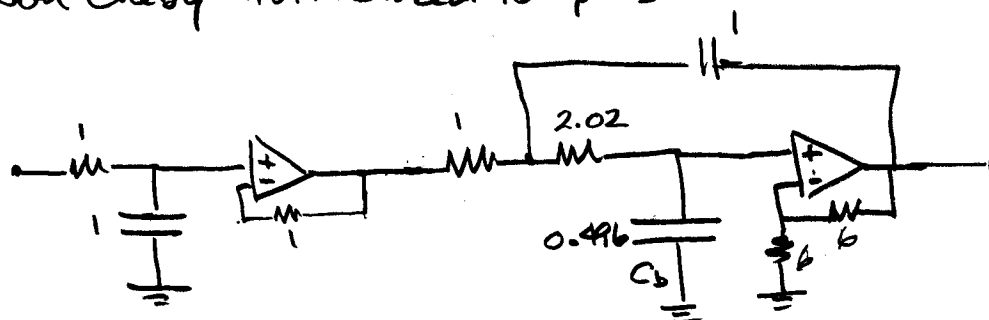


→ Comparison with example on p. 5.3.8 shows that a 3rd order Chebyshev will meet the spec. Here is the normalized LP transfer function (p. 5.3.7)

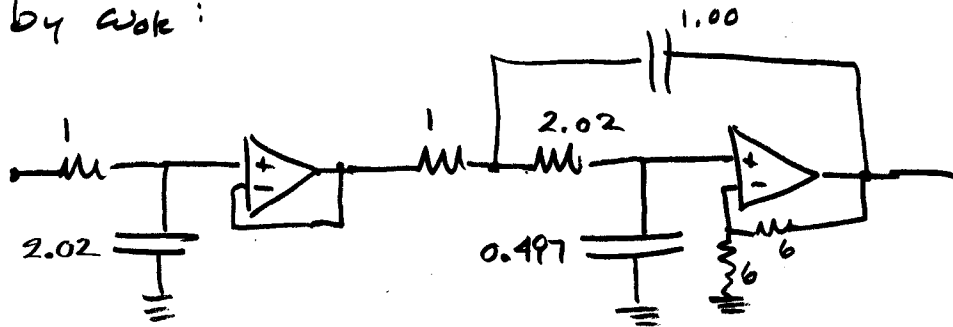
$$H(s') = \frac{0.4913}{(s' + 0.494)(s'^2 + 0.4942s' + 0.9942)}$$

	<u>section 1</u>	<u>section 2</u>
ω_0	0.494	0.997
Q		2.02

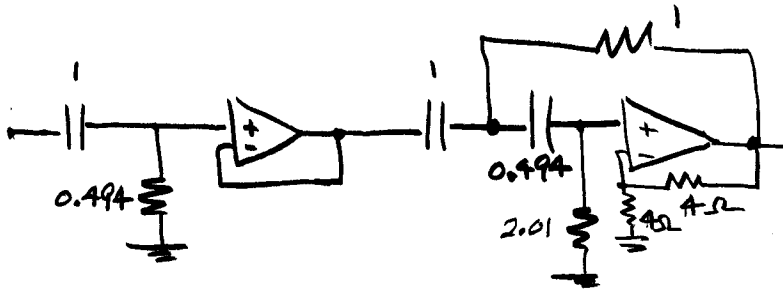
→ Non-Cheby normalized lowpass (p. 5.5.4)



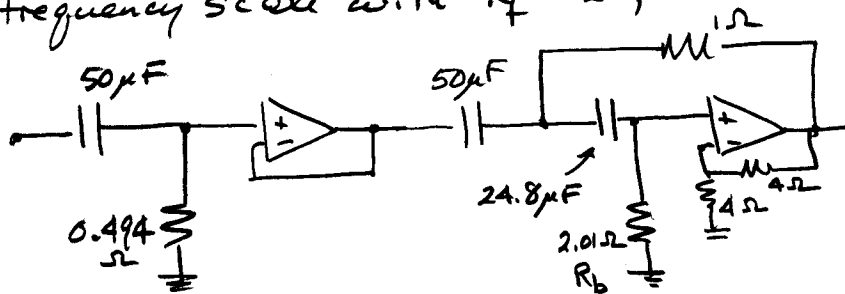
→ make it normalized ($\omega_p = 1$) Cheby lowpass, scale C's by ω_{ok} :



→ make it normalized ($\omega_p = 1$) Cheby highpass.



→ frequency scale with $K_f = 20,000$



then impedance scale.

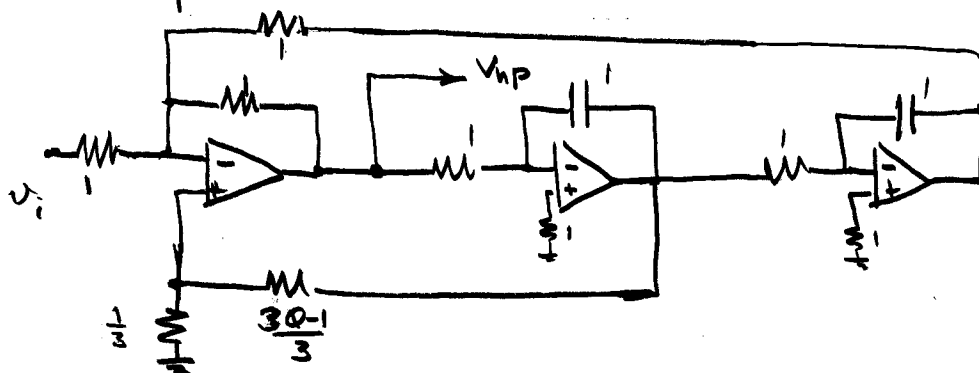
→ to do the transformation of circuit, bottom of p 5.7.7, use the one step method on p. 5.7.6. For example,

$$C_b \text{ on p 5.7.7 becomes } R_b = \frac{\omega_{o2}}{C_b} = \frac{\omega_{o2}}{1/Q_2} = 0.997 \cdot 2.02 = 2.01 \Omega$$

- With state variable filters, it's much easier, since they inherently provide the highpass transfer function

$$H(s) = \frac{s^2}{s^2 + \frac{1}{Q}s + 1} \quad (\text{normalized to } \omega_0 = 1)$$

See p. 5.6.11:



So do this:

- transform HP spec to normalized LP
- select $H'(s')$ polynomials, normalized, $\omega_p' = 1$
- calculate Q_k, ω_{0k} for each section
- for each section, select components in proto circuit above by setting Q_k , then frequency scaling by ω_p/ω_{0k} (ω_p the original HP passband). Justification: pole movement p 5.7.3

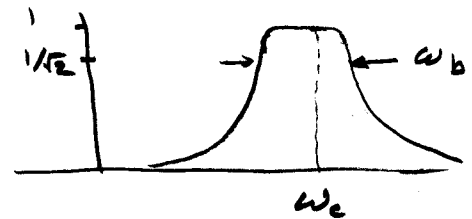
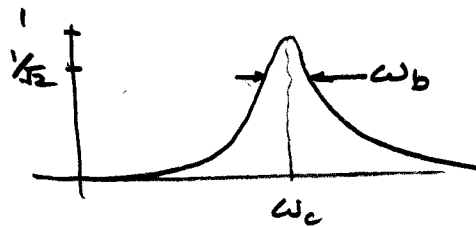
The procedure needs a little tweak for elliptic filters, which have zeros, too.

Lowpass to Bandpass

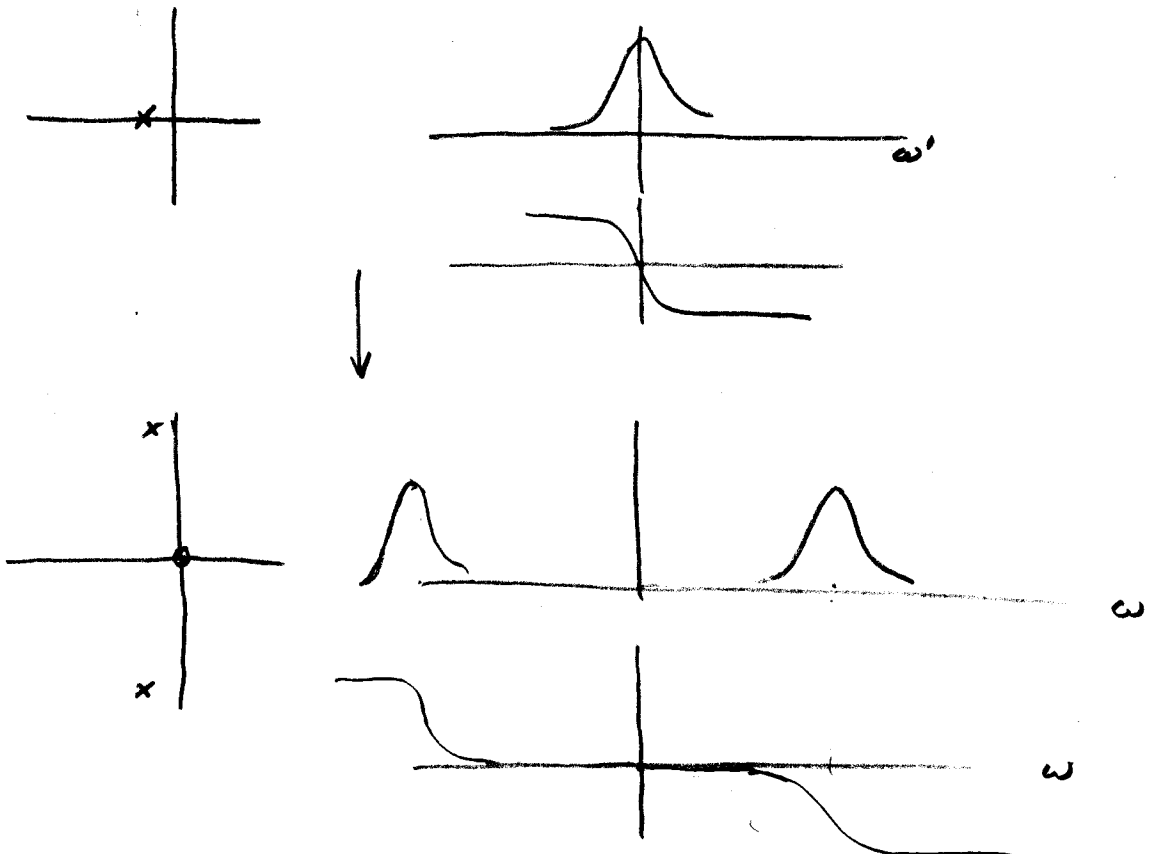
- If we have a lowpass transfer function normalized to unit bandwidth $H'(s')$, substitute

$$s' = \frac{s^2 + \omega_c^2}{s\omega_b}$$

ω_c centre freq (geometric)
 ω_b 3 dB bw

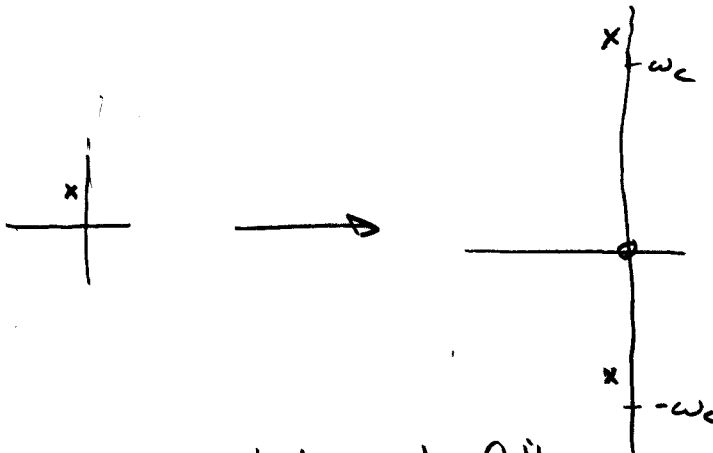


- We saw this on p 4.2.9, taking 1st order lowpass to 2nd order bpass

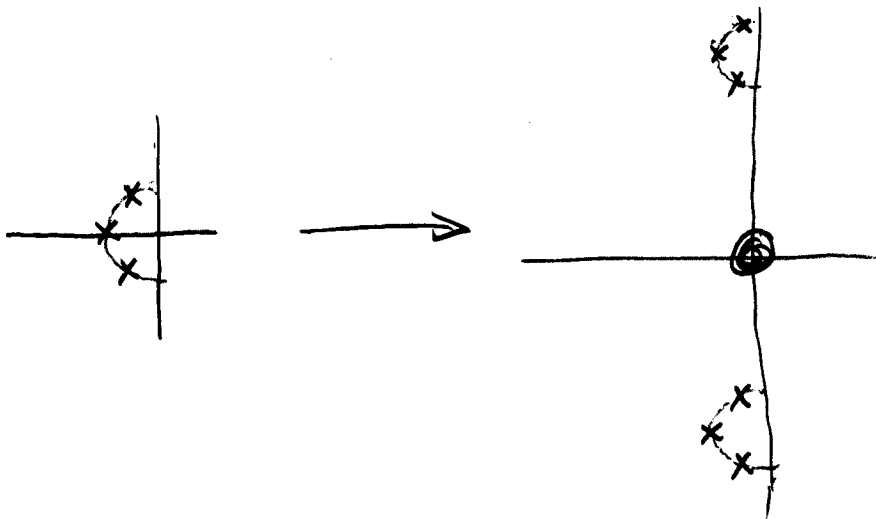


- Each pole of a lowpass splits into two and picks up a zero:

$$\frac{-p_i}{s - p_i} = \frac{-p_i}{\frac{s^2 + \omega_c^2}{s \omega_b} - p_i} = \frac{-p_i \omega_b s}{s^2 - p_i \omega_b s + \omega_c^2}$$



and more elaborate filters do this:

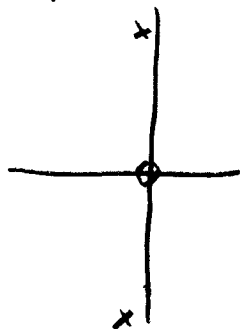


So filter order doubles

- We won't get into bandpass circuit design in this course (consult a reference).

However, you can see from the pole zero diagram on the previous page that

- it can be decomposed to quadratic bandpass sections



- and that numerical accuracy and component tolerances are tight, in order to place poles correctly



not

