Real Time and Embedded Systems

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Opening Thoughts

"Programming today is a race between software engineers striving to build bigger and better idiot-proof programs, and the Universe trying to produce bigger and better idiots. So far, the Universe is winning."

- Author Rick Cook, The Wizardry Compiled

Slide Set Overview

• What is the "Kernel"?

Microkernels and Monolithic kernels

- QNX
- Linux/PetaLinux

The KERNEL

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• The kernel is the ...



- Abstracts low-level system resources from applications
- Parts of the OS critical to its correct operation
 - Operates in supervisor mode
 - Everything else is in user mode
- Operates as trusted software:
 - Intended to implement protection mechanisms that cannot be changed through actions of untrusted software
- Decides which thread runs

- Starts the execution of the selected thread
 AKA <u>switches context</u> to the selected thread
- Context switching threads involves
 - Saving the currently running thread's registers and other context information
 - Loading the new thread's registers and context into the CPU
- What does the context switch remind you of?

Context for Process/Thread Context Switches: Recall Context Switches for subroutines and interrupts

- "Branch subroutine" (ie bsr)
 - Save PC and registers used on stack

- Interrupts (ie traps)
 - Save PC, registers used, AND SR on stack

- Keeps track of the state of all threads for thread scheduling
- Possible thread states:
 - Running
 - means the thread is actively running on the CPU
 - Ready
 - means that the thread *could* run right now

- Possible Thread States (cont'd):
 - Blocked
 - Thread is waiting for something to happen
 - There are multiple reasons a thread can end up in a blocked state
 - The kernel keeps track of why a thread can't run

Types of Kernels

Types of Kernels

- Monolithic kernels

 Linux, UNIX, MS-DOS
- Microkernels
 - QNX, Mach, CHORUS, GNU/Hurd, L4...
 - Windows NT was "supposed" to be, but not
- Other kernel types

Monolithic Kernels

- The entire kernel is run in the kernel space in supervisor mode
- Uses a set of primitives or system calls to implement operating system services such as:
 - process management,
 - concurrency, and
 - memory management
 - … all in kernel mode

- The code integration is very tight and difficult to do correctly
- Since all the modules run in the same address space, a bug in one module can crash the whole system.
- When done well, the tight internal integration of components makes a good monolithic kernel highly efficient.

Monolithic Kernel: "The layers in a Linux System"

Monolithic Kernel: The "Structure of the Linux Kernel"

Microkernels

- Provides no operating-system services at all (pure form)
 - only the *mechanisms* needed to implement such services including:
 - low-level address space management,
 - thread management, and
 - inter-process communication
- Designed to be Modular and Small

- It is the only part of the system executing in kernel mode
- The actual operating-system services are provided by user mode servers including:
 - device drivers,
 - protocol stacks,
 - file systems, and
 - the user interface
 - ... outside the kernel

Microkernel Structure



- There are other kernels, but you don't need to worry about them
- If you are interested, check out:
 - Hybrid Kernels
 - Nanokernel
 - Exokernel

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- The higher-level OS functionality is provided by:
 - A tiny kernel that provides minimal services
 - A team of <u>optional</u> cooperating processes
- The QNX kernel does not have many typical OS services
 - These are provided by optional processes

- Optional system processes could include:
 - Filesystem managers
 - Character device managers
 - Graphical user interface (Photon)
 - Native network manager
 - TCP/IP
- System processes are essentially the same as user-written applications



- The Kernel provides:
 - Thread services
 - via POSIX primitives
 - Signal services
 - via POSIX primitives
 - Synchronization services
 - via POSIX primitives

- The Kernel provides (cont'd):
 - Timer services
 - via POSIX
 - Scheduling services
 - via POSIX realtime scheduling algorithms
 - Process management services
 - Process manager + kernel = procnto
 - Manages processes, memory, and pathname space



- The Kernel provides (cont'd):
 - Message-passing services
 - The kernel routes all messages between all threads in the system
- Inter-Process Communication (IPC) services
 - Allows communication between all processes (application or device drivers)

- Unlike threads, the kernel is never scheduled for execution
 - The code in the kernel is only executed as the result of:
 - an explicit kernel call,
 - an exception, or
 - a response to a hardware interrupt

Linux/PetaLinux

PetaLinux

- PetaLinux 2.1 implements a full Linux Kernel
 - Version 2.6.37; updates include a device tree

- Therefore PetaLinux has many typical OS services
- Recall the "Structure of the Linux Kernel"

Linux

- System processes include:
 - Filesystem managers
 - Character device managers
 - Block device drivers
 - Network Device Drivers
 - TCP/IP protocols
- Can also include Loadable Kernel Modules (LKMs)
 - Think Dynamically Loaded Libraries (DLLs)

Linux/PetaLinux

- The PetaLinux Kernel provides:
 - Thread services
 - via POSIX primitives
 - Signal services
 - via POSIX primitives
 - Synchronization services
 - via POSIX primitives

Linux/PetaLinux

- The PetaLinux Kernel provides (cont'd):
 - Timer services
 - via POSIX
 - Scheduling services
 - via POSIX "realtime" scheduling algorithms
 - Real-time FIFO; Real-time Round Robin; Timesharing
 - Process management services & Memory Management services

- The Kernel provides (cont'd):
 - Inter-Process Communication (IPC) services
 - Allows Communication between all processes (application or device drivers)
- Message-passing services are supported via libraries
 - Check out the Message Passing Interface (MPI) functions designed for C and Fortran-77

Questions?

• What type of kernel is the QNX kernel? What about Linux?

• Why would someone today still choose to use a monolithic kernel?

Questions?

 What type of kernel should be used in Embedded and Real Time systems? Why?

 Recalling our discussion of processor architectures, why might a multi-threaded implementation of an application be slower than a single-threaded version?

Question

 What additional information has to be saved for a thread context switch from that of a context switch between subroutines or a software interrupt?

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Monolithic Kernels



Courtesy of Wikipedia

Microkernels



Courtesy of Wikipedia

Kernel-level threads vs User-level Threads

Kernel-level Threads

- Supported directly by the O/S
- The O/S has a separate thread for each process**
 - Performs O/S activities on behalf of the O/S
 - What is the name of this thread?
 - [Hint: Recall the Collaboration graph Notation discussion]
- ** At least- depends on the multi-threading model

- Performs thread creation, scheduling and management in kernel space
- Thread management inside the kernel is generally slower that in user space
 - i.e. Takes longer to create and manage kernel threads than user threads

User-level Threads

- Run on top of the kernel
- Only exist within a process
 - Cannot access a thread in a different process
 - Isolation and modularity provide reliability
- Used by programmers to handle multiple flows of control within a process

- The kernel is unaware of user-level thread
- Implemented with a thread library
 - Example?
 - Supports creation and scheduling management outside of the kernel
 - Done in user space without the kernel
 - Generally fast to create and manage