Real Time and Embedded Systems

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Slide Set Overview

- Priority
 - Inversion and Inheritance

Priority Inversion and Inheritance

Priority

- When threads have different priority levels, the higher priority threads will run first
 - This is good
- Unfortunately, sometimes a low-priority thread consumes all the available CPU time, blocking the higher-priority thread from running
 - This is known as priority inversion
 - This is bad
- How does it happen?



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- Basically, the semaphore will inherit the priority of the low priority client thread C1 and drop to priority 5

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- Solution: boost the server's priority to the highest priority of all blocked clients
- Good news:
 - In some systems, you don't have to do this (e.g. QNX does it automatically for your when you use message passing – but only one client- to – server deep)
 - The second server inherits the first server's real priority
 - We then have a priority inversion problem again (Why?)
 - In Linux, there is also a PI-futex patch that provides "rt_mutex"
 - The futex call is "normal"
 - The rt_mutex call supports priority inheritance

Questions?

• What is priority inversion

• How do we solve priority inversion?